

mikroBoard for ARM 144-pin™

User manual

All MikroElektronika's development systems represent irreplaceable tools for programming and developing microcontroller-based devices. Carefully chosen components and the use of machines of the last generation for mounting and testing thereof are the best guarantee of high reliability of our devices. Due to simple design, a large number of add-on modules and ready to use examples, all our users, regardless of their experience, have the possibility to develop their project in a fast and efficient way.

Development system

 **MikroElektronika**

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The primary aim of our company is to design and produce high quality electronic products and to constantly improve the performance thereof in order to better suit your needs.



Nebojsa Matic
General Manager

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1. General information

MikroBoard for ARM 144-pin is primarily intended to be connected to the EasyARM v6 development system but can also be used as a stand-alone device. The board features the LPC2214 microcontroller, flash module, USB connector, microSD connector, JTAG connector, USB UART, voltage regulator and connectors that enable connection with the development system.

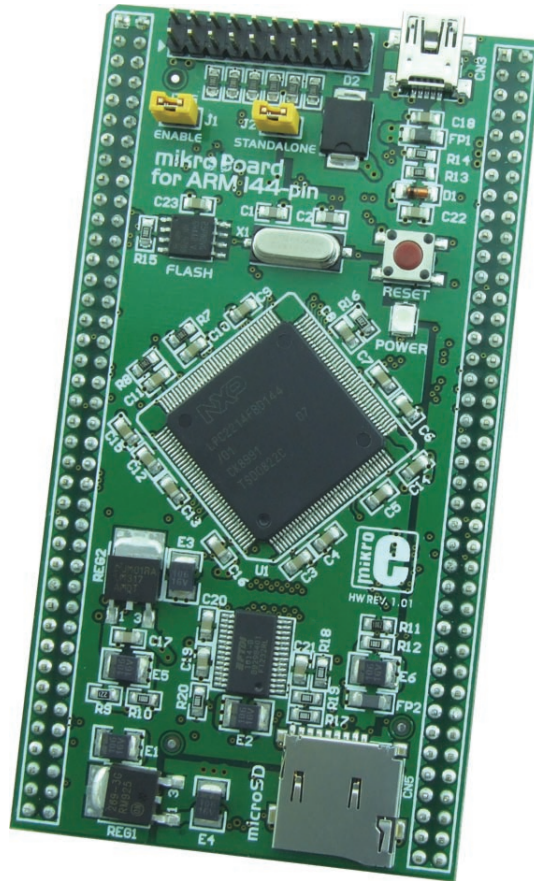


Figure 1-1: mikroBoard for ARM 144-pin

2. LPC2214 microcontroller

The LPC2214 microcontroller in 144-pin LQFP package is soldered on the mikoBoard for ARM 144-pin. Some of its key features are:

- 16/32-bit ARM7TDMI-S microcontroller in a LQFP144 package
- 16 kB on-chip static RAM and 256 kB on-chip flash program memory. 128-bit wide interface/accelerator enables high speed 60 MHz operation.
- In-System Programming (ISP) and In-Application Programming (IAP) via on-chip bootloader software.

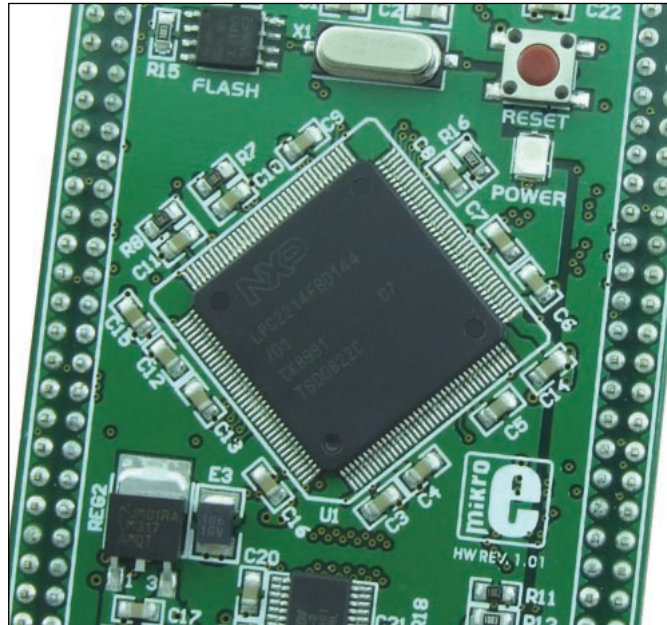


Figure 2-1: LPC2214 microcontroller

LPC2214 is connected to on board modules via pins which are also connected to CN1 and CN2 connectors. These two connectors enable the board to be connected to the EasyARM v6 development system or some other device.

3. Programming the microcontroller

The microcontroller can be programmed with a bootloader or the JTAG programmer. The use of bootloader is enabled due to the bootloader code that is loaded into the microcontroller. In order to program the microcontroller with the bootloader, it is necessary to connect the board to a PC via the CN3 connector and USB cable, Figure 3-1. A .hex code is transferred from the PC to the microcontroller by using some of the bootloader programs, such as Flash Magic.

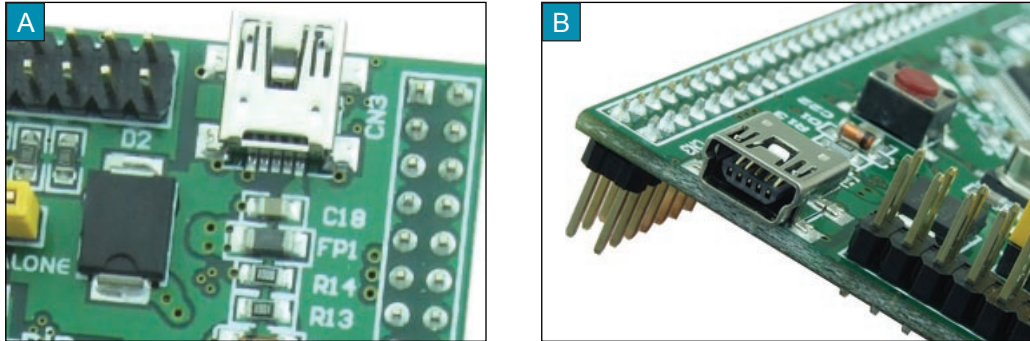


Figure 3-1: USB connector for programming

The CN3 USB connector is connected to the UART module built into the microcontroller via FTDI module (FT232RL).

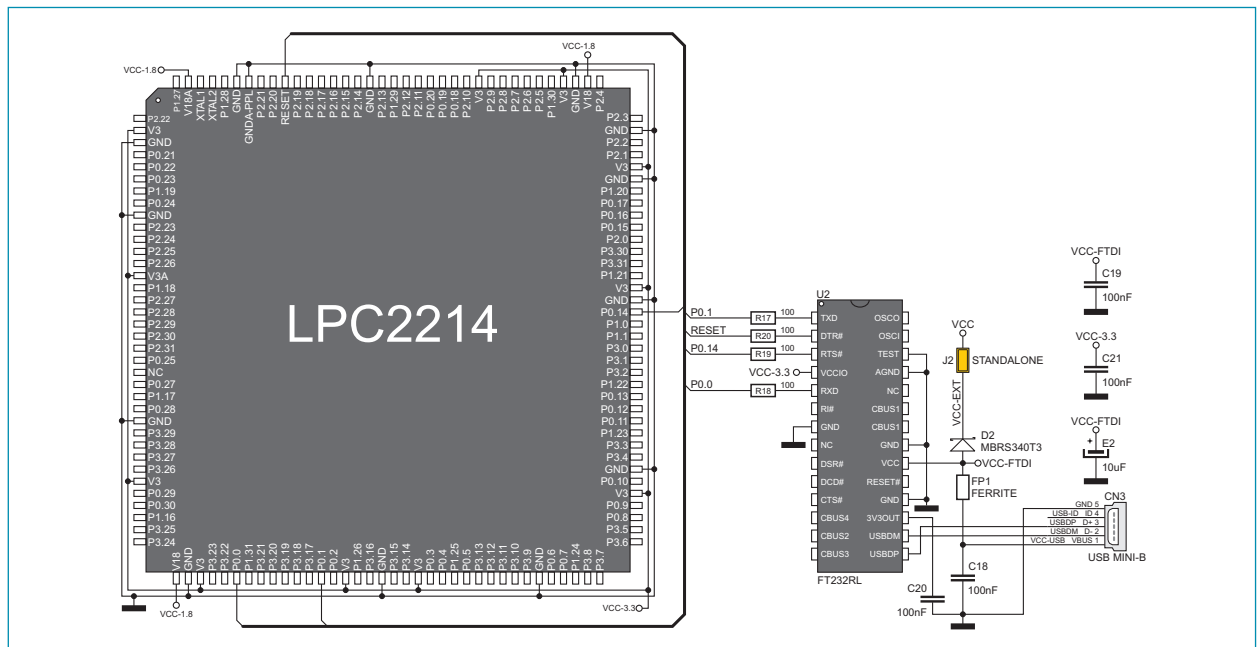
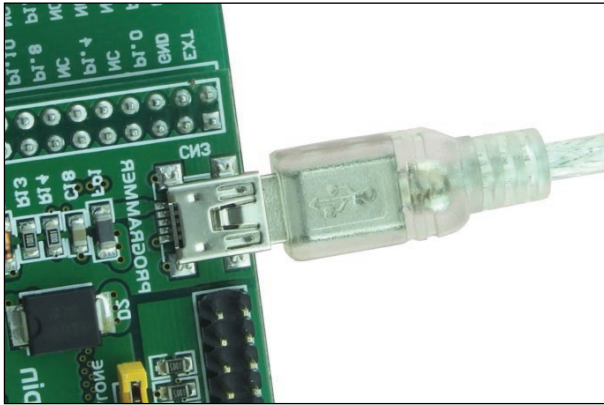


Figure 3-2: USB UART module connection schematic

When the mikroBoard for ARM 144-pin operates as a stand-alone device, it is necessary to place jumper J2 on the board. If the board is connected to the EasyARM v6 development system, jumper J2 should be removed.

In next few steps is explained how to program microcontroller with bootloader via Flash Magic application.

STEP 1: Connect the system to a PC



Connect the mikroBoard for ARM 144-pin to available USB port on your PC.

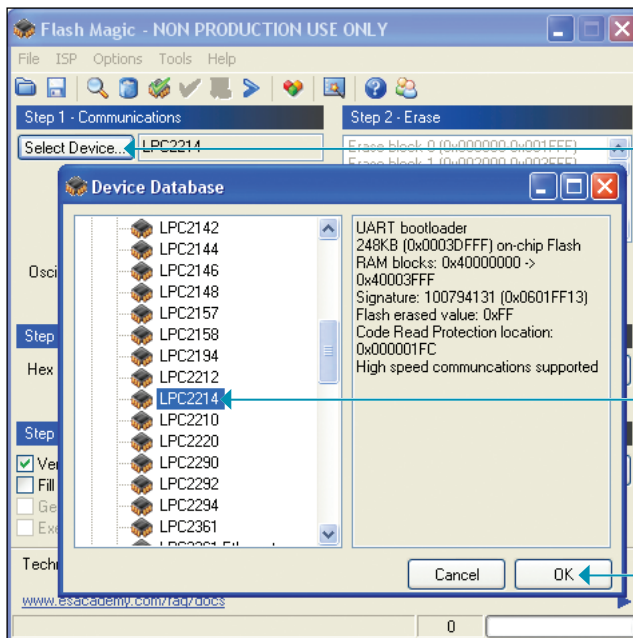
STEP 2: Start Flash Magic

Download the Flash Magic application from <http://www.flashmagictool.com/download.html&d=FlashMagic.exe> and install it on your PC

When the installation is finished double click on the Flash Magic icon



STEP 3: Select MCU



Click on the Select Device button

Select MCU from the list

Click OK

STEP 4: Settings

The screenshot shows the mikroC IDE configuration dialog with two tabs: "Step 1 - Communications" and "Step 2 - Erase".

Step 1 - Communications:

- Select Device...: LPC2214
- COM Port: COM 5
- Baud Rate: 230400
- Interface: None (ISP)
- Oscillator (MHz): 14.74568

Step 2 - Erase:

- Erase block 0 (0x000000-0x001FFF)
- Erase block 1 (0x002000-0x003FFF)
- Erase block 2 (0x004000-0x005FFF)
- Erase block 3 (0x006000-0x007FFF)
- Erase block 4 (0x008000-0x009FFF)
- Erase block 5 (0x00A000-0x00BFFF)
- Erase all Flash+Code Rd Prot
- Erase blocks used by Hex File

Annotations:

- From drop-down menu select the COM port on your PC
- Set Baud Rate to 230400
- Enter 14.74568 (if you use different oscillator set the appropriate value in MHz)

Device Manager on your PC contains information on which COM port is used for USB communication with the mikroBoard for ARM 144-pin development system. In this case the COM5 port is used.

The screenshot shows the Windows Device Manager and the "USB Serial Port (COM5) Properties" dialog.

Device Manager:

- Ports (COM & LPT)
 - Communications Port (COM1)
 - Printer Port (LPT1)
 - USB Serial Port (COM5) - Right-clicked
- Context menu: Update Driver..., Disable, Uninstall, Scan for hardware changes, Properties

USB Serial Port (COM5) Properties:

- Port Settings tab selected
- Bits per second: 9600
- Data bits: 8
- Parity: None
- Stop bits: 1
- Flow control: None
- Advanced... button

Annotations:

- From pop-up window select the Port Settings tab
- Right click on USB port, then on Properties
- Click on the Advanced... button

The screenshot shows the "Advanced Settings for COM5" dialog.

COM Port Number: COM5

USB Transfer Sizes:

- Receive (Bytes): 4096
- Transmit (Bytes): 4096

BM Options:

- Latency Timer (msec): 16

Timeouts:

- Minimum Read Timeout (msec): 0
- Minimum Write Timeout (msec): 0

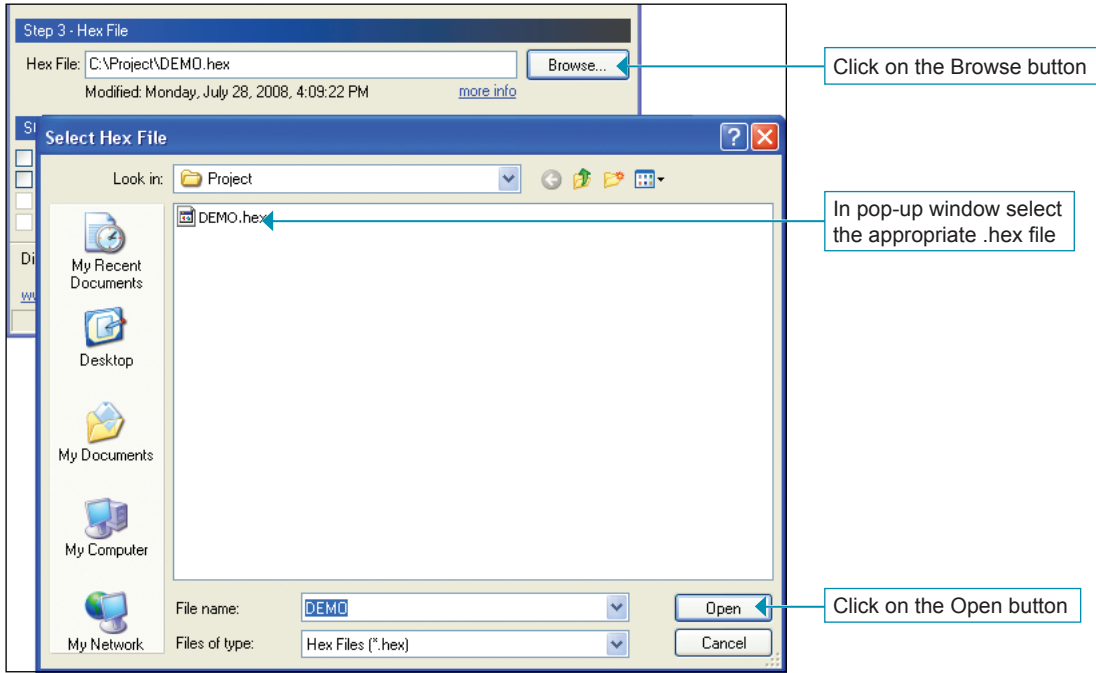
Miscellaneous Options:

- Serial Enumerator
- Serial Printer
- Cancel If Power Off
- Event On Surprise Removal
- Set RTS On Close
- Disable Modem Ctrl At Startup

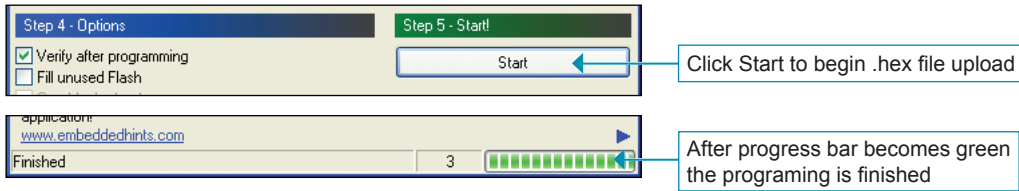
Annotations:

- In pop-up window uncheck the Serial Enumeration option and click OK

STEP 5: Browse for .hex file



STEP 6: Upload .hex file



4. Voltage regulator

The microcontroller require dual power supply: 1.8V for CPU and 3.3V for I/O. The board is powered with the 5V power supply voltage via the CN3 USB connector supplied on the board.

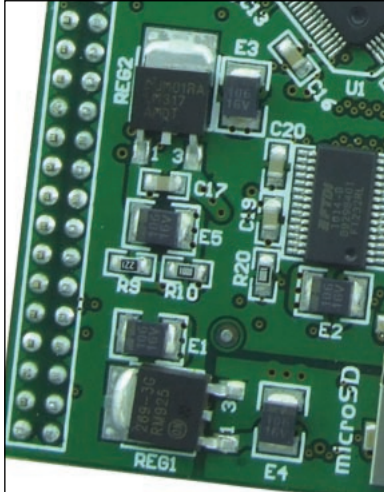


Figure 4-1: Voltage regulator

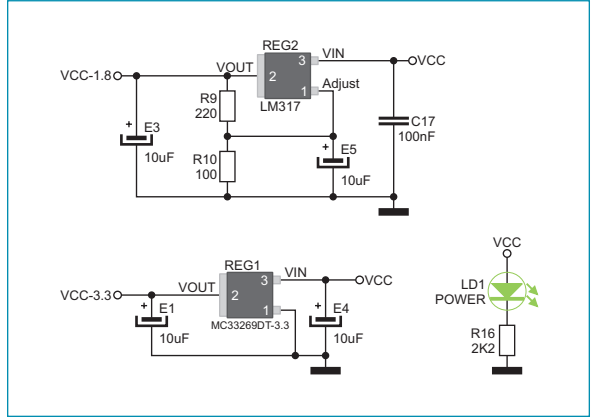


Figure 4-2: Voltage regulator connection schematic

If the board is powered by the development system (EasyARM v6), the function of the voltage regulator remains the same. In this case, it is necessary to remove jumper J2 (STANDALONE), Figure 4-3.

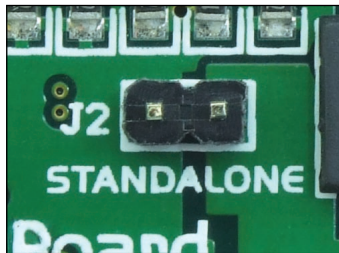


Figure 4-3: Standalone mode disabled

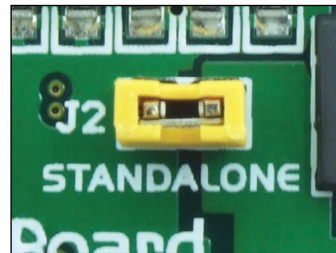


Figure 4-4: Standalone mode enabled

6. Flash module

Flash module provides additional 8Mbit of flash memory that the microcontroller can use via the Serial Peripheral Interface (SPI).

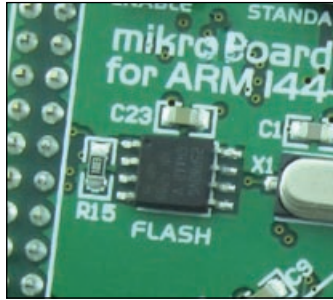


Figure 6-1: Flash memory

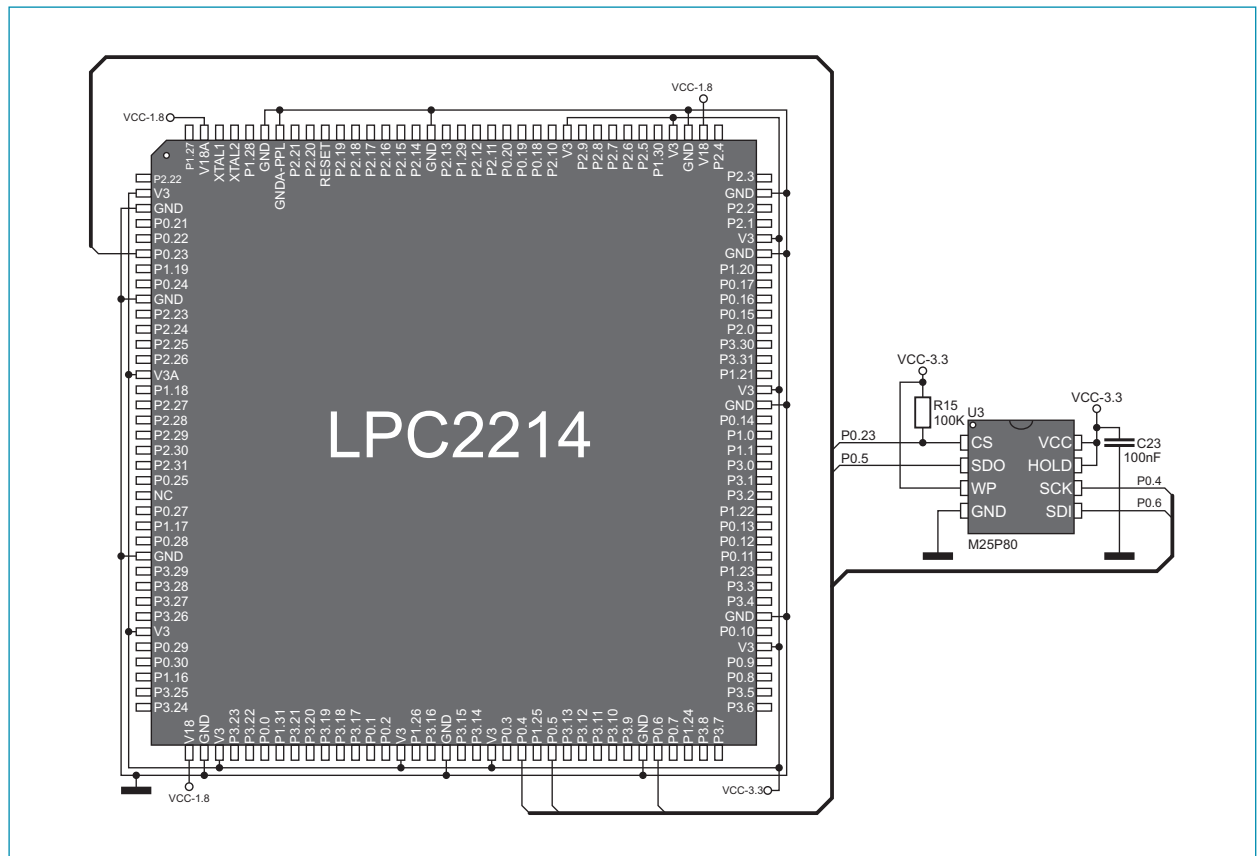


Figure 6-2: Flash module connection schematic

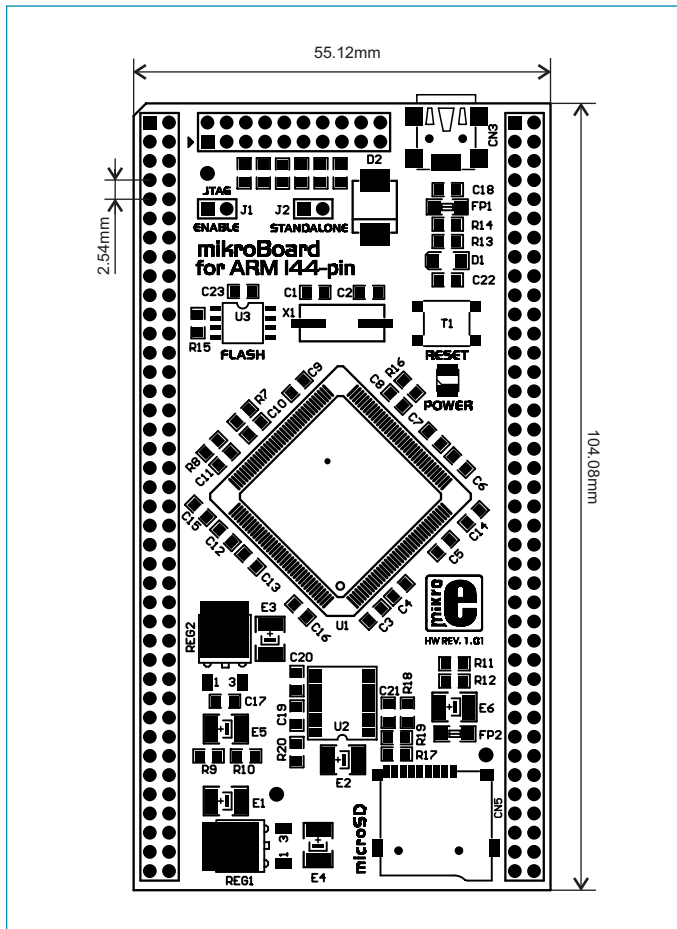


Figure 6-3: Dimensions of the mikroBoard for ARM 144-pin

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