

Hysteretic Buck High-Brightness LED Driver with High-Side Current Sensing

Features

- Hysteretic Control with High-side Current Sensing
- Wide Input Voltage Range: 4.5V to 40V
- >90% Efficiency
- Typical $\pm 5\%$ LED Current Accuracy
- Up to 2 MHz Switching Frequency
- Adjustable Constant LED Current
- Analog or Pulse-Width Modulation (PWM) Control Signal for PWM Dimming
- Overtemperature Protection
- -40°C to $+125^{\circ}\text{C}$ Operating Temperature Range

Applications

- LED Lighting Applications

General Description

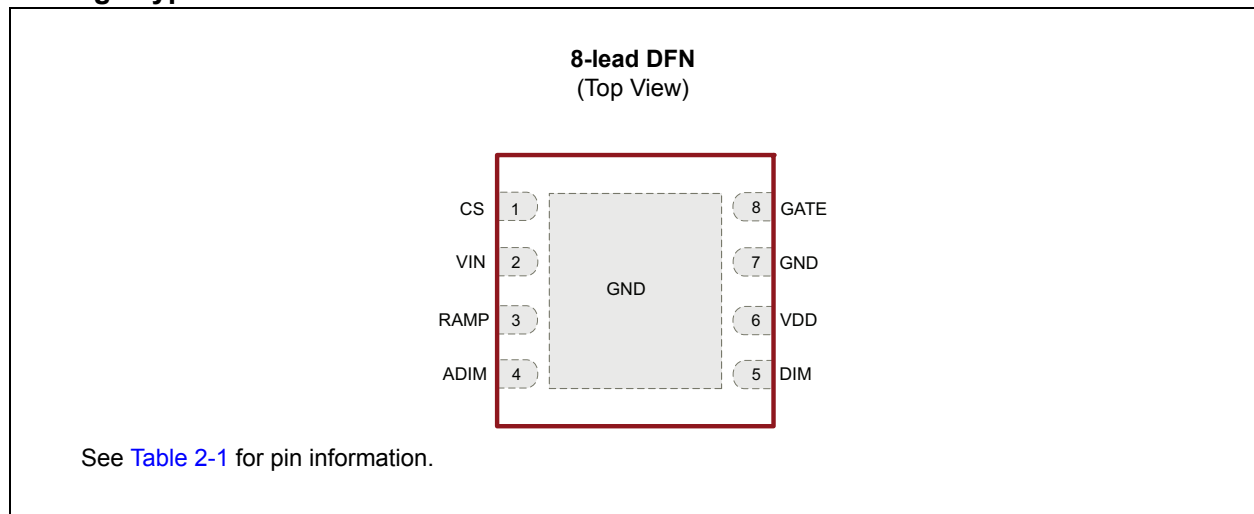
The AT9919 is a PWM controller IC designed to drive high-brightness LEDs using a buck topology. It operates from an input voltage of 4.5 VDC to 40 VDC and employs hysteretic control with a high-side current sense resistor to set the constant output current.

The operating frequency range can be set by selecting the proper inductor. Operation at high switching frequency is possible since the hysteretic control maintains accuracy even at high frequencies. This permits the use of small inductors and capacitors, minimizing space and cost in the overall system.

LED brightness control is achieved with PWM dimming from an analog or PWM input signal. Unique PWM circuitry allows true constant color with a high dimming range. The dimming frequency is programmed using a single external capacitor.

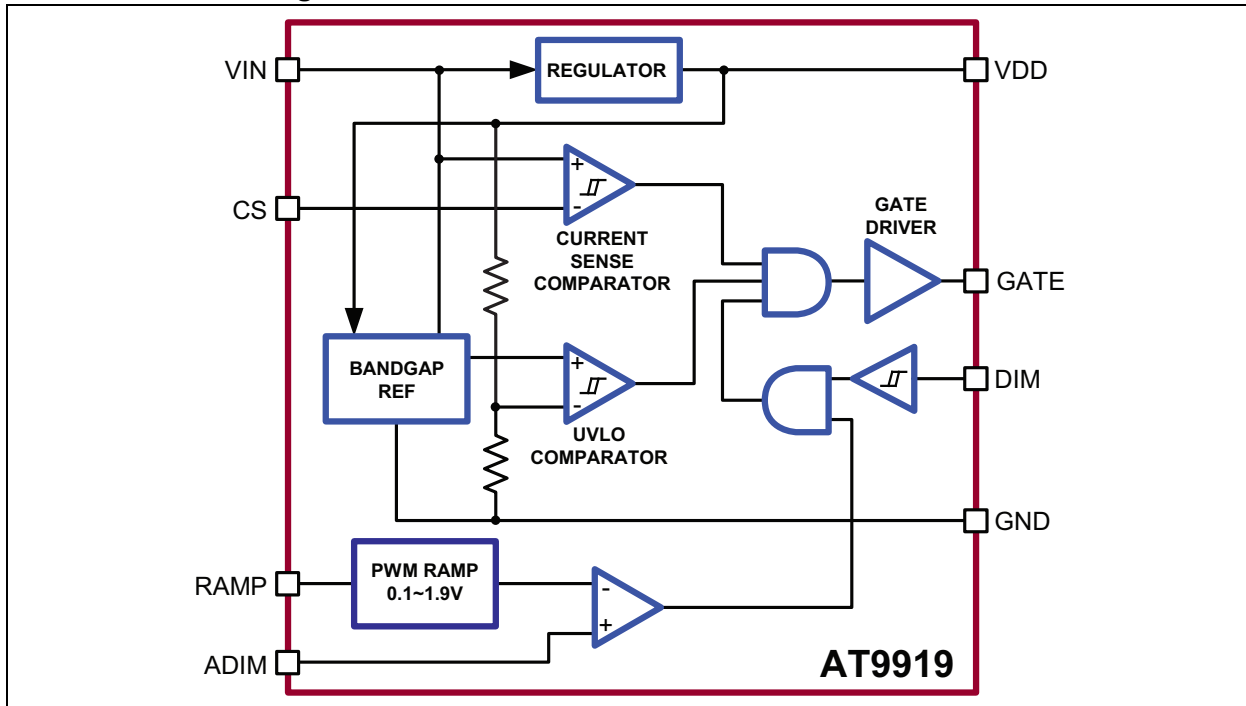
The AT9919 comes in a small, 8-lead DFN package and is qualified for LED lighting applications.

Package Type

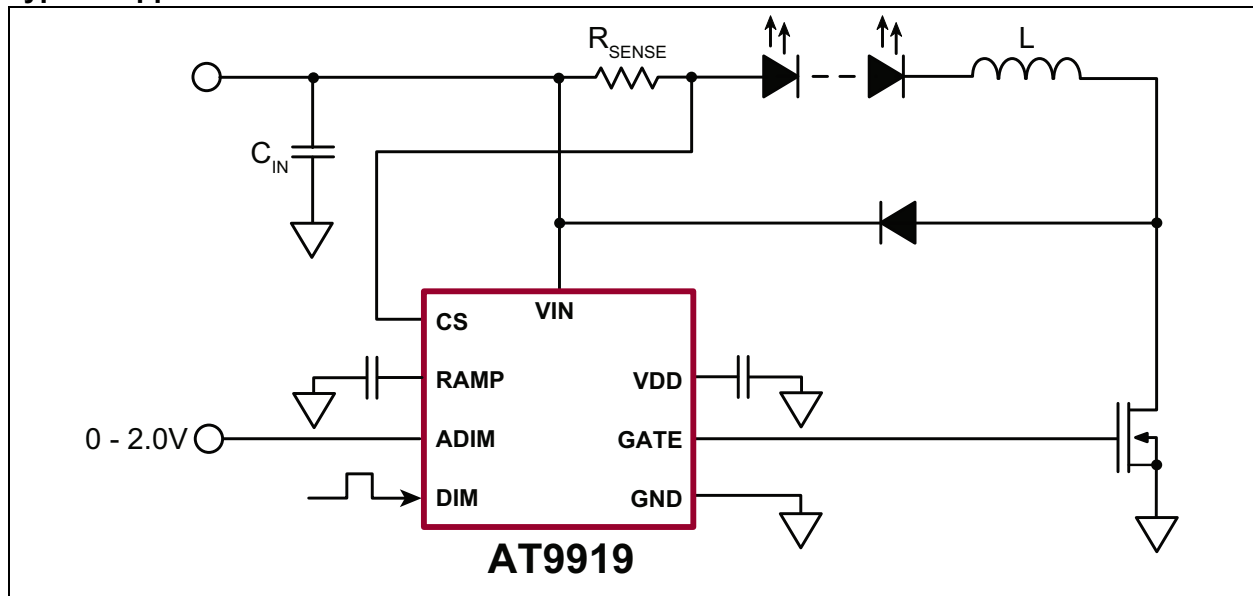


AT9919

Functional Block Diagram



Typical Application Circuit



AT9919

1.0 ELECTRICAL CHARACTERISTICS

Absolute Maximum Ratings†

V_{IN} and CS to GND	-0.3V to +45V
V_{DD} , GATE, RAMP, DIM, ADIM to GND	-0.3V to +6V
CS to V_{IN}	-1V to +0.3V
Operating Temperature Range	-40°C to +125°C
Junction Temperature	150°C
Storage Temperature Range	-65°C to 150°C
Continuous Power Dissipation ($T_A = +25^\circ\text{C}$)	1.6W

† **Notice:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at those or any other conditions above those indicated in the operational sections of this specification is not intended. Exposure to maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

Electrical Specifications: $V_{IN} = 12\text{V}$, $V_{DIM} = V_{DD}$, $V_{RAMP} = \text{GND}$, $C_{VDD} = 1\ \mu\text{F}$, $R_{CS} = 0.5\ \Omega$, $T_A = T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$ (**Note 1**) unless otherwise noted.

Parameter	Sym.	Min.	Typ.	Max.	Unit	Conditions
Input DC Supply Voltage Range	V_{IN}	4.5	—	40	V	DC input voltage
Internally Regulated Voltage	V_{DD}	4.5	—	5.5	V	$V_{IN} = 6\text{V}$ to 40V
Supply Current	I_{IN}	—	—	1.5	mA	GATE open
Shutdown Supply Current	$I_{IN,SDN}$	—	—	900	μA	DIM < 0.7V
Current Limit	$I_{IN,LIM}$	—	30	—	mA	$V_{IN} = 4.5\text{V}$, $V_{DD} = 0\text{V}$
		—	8	—		$V_{IN} = 4.5\text{V}$, $V_{DD} = 4\text{V}$
Oscillator Frequency	f_{OSC}	—	—	2	MHz	
V_{DD} Undervoltage Lockout Threshold	UVLO	—	—	4.5	V	V_{DD} rising
V_{DD} Undervoltage Lockout Hysteresis	UVLO _{HYST}	—	500	—	mV	V_{DD} falling
SENSE COMPARATOR						
Sense Voltage Threshold High	$V_{CS(HI)}$	198	230	257	mV	$(V_{IN} - V_{CS})$ rising
Sense Voltage Threshold Low	$V_{CS(LO)}$	147	170	195	mV	$(V_{IN} - V_{CS})$ falling
Average Reference Voltage	$V_{CS(AVG)}$	186	200	214	mV	$V_{CS(AVG)} = 0.5V_{CS(HI)} + 0.5V_{CS(LO)}$
Propagation Delay to Output High	t_{DPDH}	—	70	—	ns	Falling edge of $V_{IN} - V_{CS} = V_{RS(LO)} - 70\text{ mV}$
Propagation Delay to Output Low	t_{DPDL}	—	70	—	ns	Rising edge of $V_{IN} - V_{CS} = V_{RS(HI)} + 70\text{ mV}$
Current Sense Input Current	I_{CS}	—	—	1	μA	$V_{IN} - V_{CS} = 200\text{ mV}$
Current Sense Threshold Hysteresis	$V_{CS(HYST)}$	—	56	80	mV	
DIM INPUT						
Pin DIM Input High Voltage	V_{IH}	2.2	—	—	V	
Pin DIM Input Low Voltage	V_{IL}	—	—	0.7	V	
Turn-on Time	t_{ON}	—	100	—	ns	DIM rising edge to $V_{GATE} = 0.5 \times V_{DD}$, $C_{GATE} = 2\text{ nF}$
Turn-off Time	t_{OFF}	—	100	—	ns	DIM falling edge to $V_{GATE} = 0.5 \times V_{DD}$, $C_{GATE} = 2\text{ nF}$

Note 1: Limits obtained by design and characterization.

Note 2: For design guidance only

ELECTRICAL CHARACTERISTICS (CONTINUED)

Electrical Specifications: $V_{IN} = 12V$, $V_{DIM} = V_{DD}$, $V_{RAMP} = GND$, $C_{VDD} = 1 \mu F$, $R_{CS} = 0.5\Omega$, $T_A = T_J = -40^\circ C$ to $+125^\circ C$ (**Note 1**) unless otherwise noted.

Parameter	Sym.	Min.	Typ.	Max.	Unit	Conditions
GATE DRIVER						
GATE Current, Source	I_{GATE}	0.3	0.5	—	A	$V_{GATE} = GND$ (Note 2)
GATE Current, Sink		0.7	1	—	A	$V_{GATE} = V_{DD}$ (Note 2)
GATE Output Rise Time	T_{RISE}	—	40	55	ns	$C_{GATE} = 2 \text{ nF}$
GATE Output Fall Time	T_{FALL}	—	17	25	ns	$C_{GATE} = 2 \text{ nF}$
GATE High Output Voltage	$V_{GATE(HI)}$	$V_{DD} - 0.5$	—	—	V	$I_{GATE} = 10 \text{ mA}$
GATE Low Output Voltage	$V_{GATE(LO)}$	—	—	0.5	V	$I_{GATE} = -10 \text{ mA}$
OVERTEMPERATURE PROTECTION						
Over Temperature Trip Limit	T_{OT}	128	140	—	$^\circ C$	Note 2
Temperature Hysteresis	ΔT_{HYST}	—	60	—	$^\circ C$	Note 2
ANALOG CONTROL OF PWM DIMMING						
Dimming Frequency	f_{RAMP}	130	—	300	Hz	$C_{RAMP} = 47 \text{ nF}$
		550	—	1250		$C_{RAMP} = 10 \text{ nF}$
RAMP Threshold, Low	V_{LOW}	—	0.1	—	V	
RAMP Threshold, High	V_{HIGH}	1.8	—	2.1	V	
ADIM Offset Voltage	V_{OS}	-35	—	+35	mV	

Note 1: Limits obtained by design and characterization.

2: For design guidance only

TEMPERATURE SPECIFICATIONS

Parameter	Sym.	Min.	Typ.	Max.	Unit	Conditions
TEMPERATURE RANGE						
Operating Temperature	T_A	-40	—	+125	$^\circ C$	
Junction Temperature	T_J	—	—	+150	$^\circ C$	
Storage Temperature	T_S	-65	—	+150	$^\circ C$	
PACKAGE THERMAL RESISTANCE						
8-lead DFN	θ_{JA}	—	+37	—	$^\circ C/W$	

AT9919

2.0 PIN DESCRIPTION

The details on the pins of AT9919 are listed on [Table 2-1](#). Refer to [Package Type](#) for the location of pins.

TABLE 2-1: PIN FUNCTION TABLE

Pin Number	Pin Name	Description
1	CS	Current sense input. Senses LED string current.
2	VIN	Input voltage 4.5V to 40V DC
3	RAMP	Analog PWM dimming ramp output
4	ADIM	Analog 0V~2V signal input for analog control of PWM dimming
5	DIM	PWM signal input
6	VDD	Internally regulated supply voltage. Connect a capacitor from VDD to ground.
7	GND	Device ground
8	GATE	Drives GATE of the external MOSFET
TAB	GND	Must be wired to pin 7 on PCB

3.0 APPLICATION INFORMATION

3.1 General Description

The AT9919 is a step-down constant-current high-brightness LED (HB LED) driver. The device operates from a 4.5V to 40V input voltage range and provides the gate drive output to an external N-channel MOSFET. A high-side current sense resistor sets the output current, and a dedicated PWM dimming input (DIM) allows for a wide range of dimming duty ratios. The PWM dimming could also be achieved by applying a DC voltage between 0V and 2V to the analog dimming input (ADIM). In this case, the dimming frequency can be programmed using a single capacitor at the RAMP pin. The high-side current sensing scheme minimizes the number of external components while delivering LED current with a $\pm 8\%$ accuracy, using a 1% sense resistor.

3.2 Undervoltage Lockout (UVLO)

The AT9919 includes a 3.7V UVLO with 500 mV hysteresis. When V_{IN} falls below 3.7V, GATE goes low, turning off the external N-channel MOSFET. GATE goes high once V_{IN} is 4.5V or higher.

3.3 5V Regulator

V_{DD} is the output of a 5V regulator capable of sourcing 8 mA. Bypass V_{DD} to GND with a 1 μ F capacitor.

3.4 DIM Input

The AT9919 allows dimming with a PWM signal at the DIM input. A logic level below 0.7V at DIM forces the GATE_{OUTPUT} low, turning off the LED current. To turn on the LED current, the logic level at DIM must be at least 2.2V.

3.5 ADIM and RAMP Inputs

The PWM dimming scheme can also be implemented by applying an analog control signal to the ADIM pin. If an analog control signal of 0V~2.0V is applied to ADIM, the device compares this analog input to a voltage ramp to pulse width modulate the LED current. Connecting an external capacitor to RAMP programs the PWM dimming ramp frequency. See Equation 3-1.

EQUATION 3-1:

$$f_{PWM} = \frac{1}{C_{RAMP} \times 120k\Omega}$$

The DIM and ADIM inputs can be used simultaneously. In such case, a $f_{PWM(MAX)}$ lower than the frequency of the dimming signal at DIM must be selected. The smaller dimming duty cycle of ADIM and DIM will determine the GATE signal.

When the analog control of PWM dimming feature is not used, RAMP must be wired to GND and ADIM should be connected to V_{DD} .

One possible application of the ADIM feature may include protection of the LED load from overtemperature by connecting an NTC thermistor to ADIM as shown in Figure 3-1.

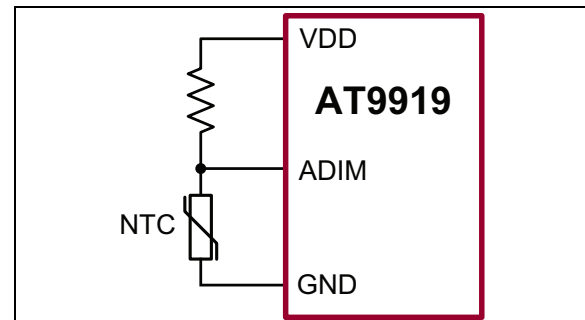


FIGURE 3-1: Overtemperature Protection using ADIM Pin.

3.6 Setting LED Current with the External Resistor (R_{SENSE})

The output current in the LED is determined by the external current sense resistor (R_{SENSE}) connected between V_{IN} and CS. Disregarding the effect of the propagation delays, the sense resistor can be calculated as seen in Equation 3-2.

EQUATION 3-2:

$$R_{SENSE} \approx \left(\frac{1}{2}\right) \times \left(\frac{V_{RS(HD)} + V_{RS(LO)}}{I_{LED}}\right) = \frac{200mV}{I_{LED}}$$

3.7 Selecting Buck Inductor (L)

The AT9919 regulates the LED output current using an input comparator with hysteresis. (See Figure 3-2.) As the current through the inductor ramps up, and the voltage across the sense resistor reaches the upper threshold, the voltage at GATE goes low, turning off the external MOSFET. The MOSFET turns on again when the inductor current ramps down through the freewheeling diode until the voltage across the sense resistor equals the lower threshold.

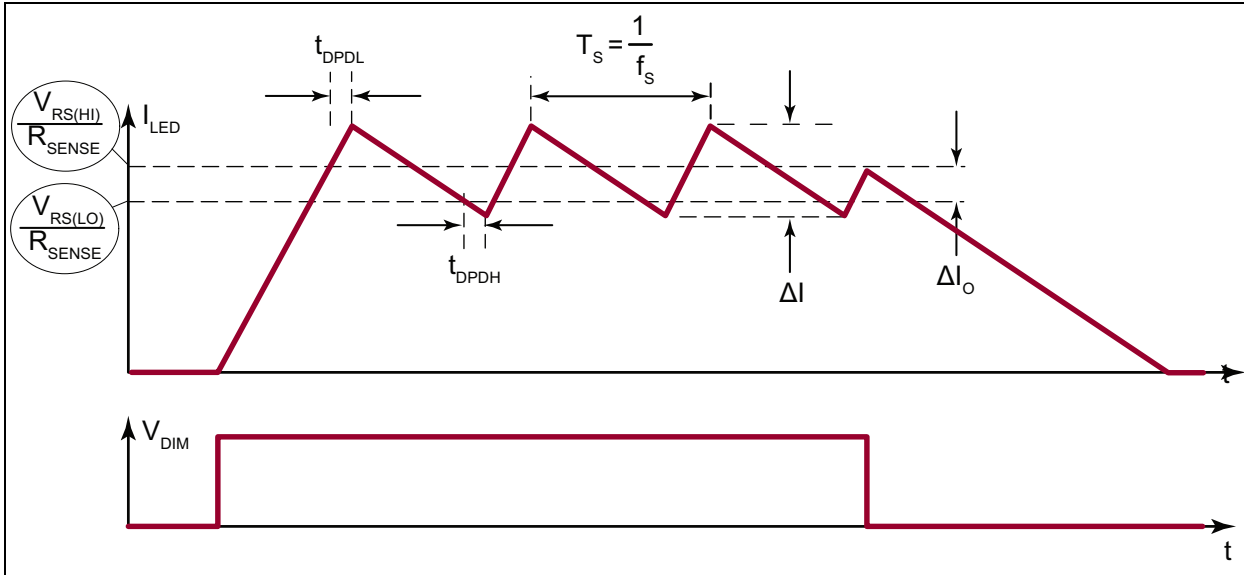


FIGURE 3-2: Inductor Current Waveform.

Equation 3-3 shows how to determine the inductor value for a desired operating frequency (f_s).

EQUATION 3-3:

$$L = \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{f_s V_{IN} \Delta I_O} - \frac{(V_{IN} - V_{OUT}) \times t_{DPDL}}{\Delta I_O} - \frac{V_{OUT} t_{DPDH}}{\Delta I_O}$$

Where:

$$\Delta I_O = \frac{V_{RS(HI)} - V_{RS(LO)}}{R_{SENSE}}$$

and t_{DPDL} and t_{DPDH} are the propagation delays.
Note that the current ripple (ΔI) in the inductor (L) is greater than ΔI_O .

The current ripple in the inductor (L) can be calculated with Equation 3-4.

EQUATION 3-4:

$$\Delta I = \Delta I_O + \frac{(V_{IN} - V_{OUT}) \times t_{DPDL}}{L} + \frac{V_{OUT} t_{DPDH}}{L}$$

For proper inductor selection, note that the maximum switching frequency occurs at the highest V_{IN} and $V_{OUT} = V_{IN}/2$.

3.8 MOSFET Selection

MOSFET selection is based on the maximum input operating voltage V_{IN} , output current I_{LED} and operating switching frequency. Choose a MOSFET that has a higher breakdown voltage than the maximum operation voltage, low $R_{DS(ON)}$ and low total charge for

better efficiency. MOSFET threshold voltage must be adequate when operated at the low end of the input voltage operating range.

3.9 Freewheeling Diode Selection

The forward voltage of the freewheeling diode should be as low as possible for better efficiency. A Schottky diode is a good choice as long as the breakdown voltage is high enough to withstand the maximum operating voltage. The forward current rating of the diode must be at least equal to the maximum LED current.

3.10 LED Current Ripple

The LED current ripple is equal to the inductor current ripple. In cases when a lower LED current ripple is needed, a capacitor can be placed across the LED terminals.

3.11 PCB Layout Guidelines

Careful PCB layout is critical to achieving low switching losses and stable operation. Use a multilayer board whenever possible for better noise immunity. Minimize ground noise by connecting high-current ground returns, the input bypass capacitor ground lead and the output filter ground lead to a single point (star ground configuration). The fast di/dt loop is composed of the input capacitor C_{IN} , the freewheeling diode and the MOSFET. To minimize noise interaction, this loop area should be as small as possible. Place R_{SENSE} as close as possible to the input filter and V_{IN} . For better noise immunity, a Kelvin connection is strongly recommended between CS and R_{SENSE} . Connect the exposed tab of the IC to a large area ground plane for improved power dissipation.

AT9919

4.0 PACKAGING INFORMATION

4.1 Package Marking Information

8-lead DFN

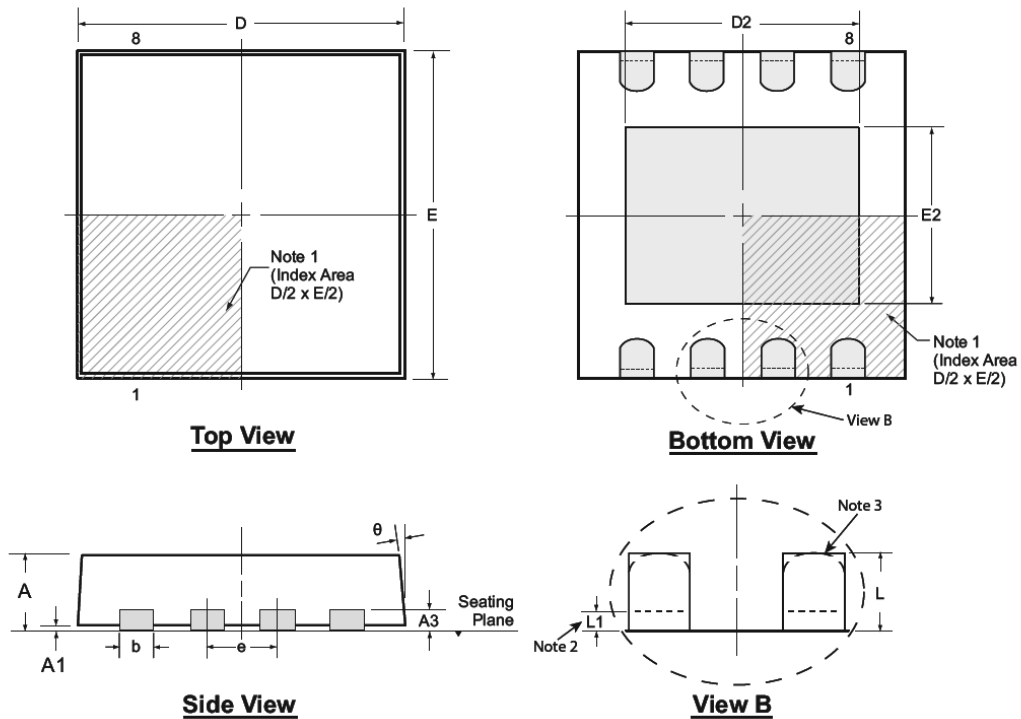
Example

XXXX
YYWW
●NNN

9919
1612
●373

Legend:	XX...X	Product Code or Customer-specific information
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week '01')
	NNN	Alphanumeric traceability code
	(e3)	Pb-free JEDEC® designator for Matte Tin (Sn)
	*	This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.
Note:	In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for product code or customer-specific information. Package may or not include the corporate logo.	

8-Lead DFN Package Outline (K7) 3.00x3.00mm body, 0.80mm height (max), 0.65mm pitch



Note: For the most current package drawings, see the Microchip Packaging Specification at www.microchip.com/packaging.

Notes:

1. A Pin 1 identifier must be located in the index area indicated. The Pin 1 identifier can be: a molded mark/identifier, an embedded metal marker, or a printed indicator.
2. Depending on the method of manufacturing, a maximum of 0.15mm pullback (L1) may be present.
3. The inner tip of the lead may be either rounded or square.

Symbol	A	A1	A3	b	D	D2	E	E2	e	L	L1	θ	
Dimension (mm)	MIN	0.70	0.00	0.20 REF	0.25	2.85*	1.60	2.85*	1.35	0.65 BSC	0.30	0.00*	0°
	NOM	0.75	0.02		0.30	3.00	-	3.00	-		0.40	-	-
	MAX	0.80	0.05		0.35	3.15*	2.50	3.15*	1.75		0.50	0.15	14°

JEDEC Registration MO-229, Variation WEEC-2, Issue C, Aug. 2003.

* This dimension is not specified in the JEDEC drawing.

Drawings not to scale.

AT9919

NOTES:

APPENDIX A: REVISION HISTORY

Revision A (October 2016)

- Converted Supertex Doc# DSFP-AT9919 to Microchip DS20005595A.
- Changed packaging quantity of 8-lead DFN from 3000/Reel to 3300/Reel.
- Made minor text changes throughout the document.

AT9919

PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, contact your local Microchip representative or sales office.

<u>PART NO.</u>	<u>XX</u>	-	<u>X</u>	-	<u>X</u>
Device	Package Options		Environmental		Media Type
Device:	AT9919	=	Hysteretic Buck High-Brightness LED Driver with High-Side Current Sensing		
Package:	K7	=	8-lead (3x3) DFN		
Environmental:	G	=	Lead (Pb)-free/RoHS-compliant Package		
Media Type:	(blank)	=	3300/Reel for a K7 Package		

Example:	
a) AT9919K7-G:	Hysteretic Buck High-Brightness LED Driver with High-Side Current Sensing, 8-lead (3x3) DFN Package, 3300/Reel

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